

Iraqi Journal for Computer Science and Mathematics

Journal Homepage: http://journal.esj.edu.iq/index.php/IJCM ISSN: 2788-7421 p-ISSN: 2958-0544



# Approximation of an Inertial Iteration Method for a Set-Valued Quasi Variational Inequality

# Mohammad Akram<sup>1,\*<sup>10</sup></sup>

<sup>1</sup>Department of Mathematics, Faculty of Science, Islamic University of Madinah, 42351, Madinah, Saudi Arabia

\*Corresponding Author: Mohammad Akram

DOI: https://doi.org/10.52866/ijcsm.2024.05.02.007 Received Jan 2024; Accepted March 2024; Available online march 2024

**ABSTRACT:** In this article, a projection type two step inertial iterative scheme for investigating set-valued quasi variational inequality in real Banach spaces is designed. We manifest the existence result and verified by an illustrative example. Also, we estimate the approximate solution of a set-valued quasi variational inequality by analyzing the convergence of the proposed inertial iterative algorithm. Further, an extended Weiner-Hopf equation is considered and substantiated that it is analogous to the extended set-valued quasi variational inequality. Finally, we investigate the extended Weiner-Hopf equation by analyzing the convergence of the composed iterative scheme.

**Keywords:** Set-valued quasi variational inequality; inertial iterative algorithm; strong convergence; Weiner-Hopf equation

# **1. INTRODUCTION**

Assume that  $\Omega \neq \phi$  is a closed convex set in a Banach space  $\mathcal{B}$  and  $\psi : \mathcal{B} \to \mathcal{B}$  be a nonlinear mapping. The variational inequality problem (VIP) is to observe a component  $\hat{a} \in \Omega$  so that

$$\langle \varphi(\hat{a}), \hat{b} - \hat{a} \rangle \ge 0, \forall \hat{b} \in \Omega.$$
<sup>(1)</sup>

It is commonly known that VIP introduced by Stampacchia [50] is a highly effective and useful tool for analyzing issues that arise in all diverse areas of natural sciences. Because of applicability and fruitful outcomes, VIPs have been broadened and diversified in a number of ways, see, [5, 6, 14–16, 18, 29, 39]. Among these generalizations, quasi variational inequality  $QVI(\Omega(\hat{a}), \varphi)$  is a prominent generalization which is to observe a component  $\hat{a} \in \Omega(\hat{a})$  so that

$$\langle \varphi(\hat{a}), \hat{b} - \hat{a} \rangle \ge 0, \forall \hat{b} \in \Omega(\hat{a}),$$
 (2)

where  $\Omega : \mathcal{B} \to 2^{\mathcal{B}}$  be a set-valued mapping with  $\Omega(\hat{a}) \subset \mathcal{B}, \forall \hat{a} \in \mathcal{B}$ . If  $\Omega(\hat{a}) = \Omega, \forall \hat{a} \in \mathcal{B}$ , then  $QVI(\Omega(\hat{a}), \varphi)$  reduces to VIP (1). The study of QVIs has been recognized an extremely practical and applicable field. A model of quasi variational inequalities has been used to frame a number of problems with practical applications, including free boundary problems, mechanics, economy, and stochastic impulsive control modeling, see, [8, 9, 12, 25, 26, 31]. It was demonstrated by Noor et al. [38, 41] that the obstacle boundary value problem (*OBVP*) of pointing out *w* so that

$$\begin{cases}
-w^{'''}(x) \ge \varphi(x), \text{ on } \mathcal{D} = [a_1, a_2] \\
w(x) \ge C(w), \text{ on } \mathcal{D} = [a_1, a_2] \\
[-w^{'''}(x) - \varphi(x)][w - C(w)] = 0, \text{ on } \mathcal{D} = [a_1, a_2] \\
w(a_1) = 0, w^{'}(a_1) = 0, w^{'}(a_2) = 0,
\end{cases}$$
(3)

where  $\varphi$  is continuous and C(w) represents the obstacle (cost) function can be formulated as following generalized quasi variational inequality

$$\langle \theta(w), \phi(q) - \phi(w) \rangle \ge \langle \varphi, \phi(q) - \phi(w) \rangle, \forall q \in \Omega(w).$$
 (4)

Following important lemma assures the existence of solution of  $QVI(\Omega(\hat{a}),\varphi)$ . Lemma 1. [37] Assume that the subsequent premises hold true.

- (i) Suppose  $\varphi : \mathcal{H} \to \mathcal{H}$  is  $\delta_{\varphi}$ -Lipschitz continuous and  $\varsigma$ -strongly monotone.
- (ii) The projection mapping  $P_{\Omega(\hat{a})} : \mathcal{H} \to \Omega(\hat{a})$  satisfies

$$P_{\Omega(\hat{a})}(\xi) - P_{\Omega(\hat{b})}(\xi) \le \nu ||\hat{a} - \hat{b}||, \forall \hat{a}, \hat{b}, \xi \in \mathcal{H},$$

 $(iii) \ \exists \hat{b} \geq 0 \ comply \ with \ \hat{b} + \sqrt{1-(\varsigma/\delta_\varphi)^2} < 1.$ 

Then  $QVI(\Omega(\hat{a}), \varphi)$  has a unique solution.

In case  $\Omega(\hat{a}) = \Omega$ , assumption (*ii*) holds for  $\hat{b} = 0$  and the assumption (*iii*) becomes trivial. Therefore, assuming assumption (*i*) of Lemma 1 holds, then VIP (1.1) has a unique solution, see [37]. The  $QVI(\Omega(\hat{a}), \varphi)$  was initially developed by Bensoussan and Lions [9] for addressing problems related to impulse control. QVIs bring forth an integrated framework for variation inequalities and integrated modeling of significant physical problems. Several applications and significance of QVIs include superconductivity, thermoplasticity or electrostatics [22, 23, 28], continuum and solid mechanics [10, 27, 42], transportation [11, 47], game theory [21], etc.

However, the fixed point theory has become fastest expanding research field. Numerous problems appearing in science, and engineering, particularly in ODEs, PDEs, VIs, and zeros of monotone operators have been investigated by transforming as a model of fixed point problem. The fixed point of a nonlinear mapping  $\varphi : \mathcal{B} \to \mathcal{B}$  is described as  $Fix(\varphi) = \{\hat{a} \in \mathcal{B} : \varphi(\hat{a}) = \hat{a}\}$ . Owing to the significance of fixed points numerous new iterative schemes have been designed and tackled over the last few years. The extensively researched and widely used method for determining fixed points is due to Mann iteration method [35], which is given as:

$$\mu_{n+1} = (1 - \alpha_n)\mu_n + \alpha_n \varphi(\mu_n), n \in \mathbb{N},\tag{5}$$

where  $\alpha_n \in [0, 1]$ . A few common and widely used iteration techniques include Ishikawa iteration [24], Halpern iteration [20], *S*-iteration [2].

Researchers are fascinated by the possibility of achieving enhanced convergence rates by developing iterative methods to obtain the solutions of nonlinear problems. In an attempt to obtain an increasing rate of convergence, several iterative schemes have been investigated and tested. A such attempt was made to enhance the convergence rate by adding inertial term, see, [29, 34, 45, 46, 49]. It was Polyak [43] who originated the inertial term to investigate an optimization problem. In order to acquire the inertial term the heavy ball method was employed by discretizing the following second order system:

$$\mu^{''}(t) + \psi \mu^{'}(t) + \nabla \omega(\mu(t)) = 0, \tag{6}$$

where  $\omega : \mathcal{H} \to \mathbb{R}$  is differentiable,  $\mu(t)$  represents time continuous trajectory,  $\psi(\mu(t))$  external gravitational field and  $\psi > 0$  the friction. Richardson [44] employed a relaxation method to solve a linear systems with augmented rate of convergence. In this sequel, Eckstein and Bertsekas [17] accelerated a proximal point algorithm by adding an relaxation parameter. Further by adding relaxation techniques with inertial term, Alvarez [7] proposed an iteration process to deal with convex optimization and monotone inclusion problems. In this development, Maigne [32] devised the inertial Mann iterative scheme to reckon fixed points of a nonexpansive mapping as:

$$\begin{cases} \nu_n = \mu_n + \tau_n(\mu_n + \mu_{n-1}), \\ \mu_{n+1} = (1 - a_n)\nu_n + a_n\varphi\nu_n, \forall n \in \mathbb{N}, \end{cases}$$

$$\tag{7}$$

where  $a_n$  is a relaxation factor and  $\tau_n$  is a damping term. Owing to the attraction of researchers and importance of augmented rate of convergence, so far numerous iterative methods involving single or double inertial terms have been designed and analyzed, see [1, 3, 4, 19, 48, 51?]. Recently, Çopur et al. [13] investigated  $QVI(\Omega(\hat{a}),\varphi)$  by analyzing the following inertial iteration process involving two inertial terms as follows:

$$\begin{aligned}
& \mu_n = w_n + \gamma_n(\zeta_n - \zeta_{n-1}), \\
& \nu_n = w_n + \tau_n(\zeta_n - \zeta_{n-1}), \\
& \zeta_{n+1} = (1 - a_n - b_n)\nu_n + a_n\varphi(\nu_n) + b_n\mu_n,
\end{aligned}$$
(8)

69

where  $\{\gamma_n\},\{\tau_n\}$  are sequences in (0, 1). Motivated and convinced by the acknowledged information cited in the sources mentioned above, our motive is to examine the  $EQVI(\mathcal{B},\psi,\varphi,\Psi)$ . We manifest the existence result which is validated by an illustrative example. Also, we estimate the approximate solution of  $EQVI(\mathcal{B},\psi,\varphi,\Psi)$  by analyzing the convergence of two steps inertial iterative algorithm based on (8). Further, an extended Weiner-Hopf equation is considered and substantiated that it is analogous to  $EQVI(\mathcal{B},\psi,\varphi,\Psi)$ . By implementing this equivalence, we derive the solution of  $EQVI(\mathcal{B},\psi,\varphi,\Psi)$ . Lastly, we investigate the extended Weiner-Hopf equation by analyzing the convergence of the composed scheme.

#### 2. PRELUDES AND EXISTENCE RESULTS

Let  $\mathscr{B}$  be a real Banach space equipped with norm  $\|\cdot\|$ ;  $\langle\cdot,\cdot\rangle$  is the duality pairing between  $\mathscr{B}$  and its dual space  $\mathscr{B}^*$ ; the family of closed and bounded subsets of  $\mathscr{B}$  is represented by  $CB(\mathscr{B})$  and  $2^{\mathscr{B}}$  is the power set of  $\mathscr{B}$ . The normalized duality mapping  $J: \mathscr{B} \to 2^{\mathscr{B}^*}$  is expressed as

$$J(\hat{a}) = \{\varphi \in \mathcal{B}^* : \langle \hat{a}, \varphi \rangle = \|\hat{a}\|^2 = \|\varphi\|\|^2\}, \forall \hat{a} \in \mathcal{B}$$

**Lemma 2.** For all  $e_1, e_2 \in \mathcal{B}$ ,  $J : \mathcal{B} \to \mathcal{B}^*$  is characterized by the following inequalities:

- (i)  $||e_1 + e_2||^2 \le ||e_1||^2 + 2\langle e_2, J(e_1 + e_2) \rangle;$
- (*ii*)  $\langle e_1 e_2, Je_1 Je_2 \rangle \le 2d^2 \rho_{\mathcal{B}}(4||e_1 e_2||/d);$

where,  $d = \sqrt{(||e_1||^2 + ||e_2||^2)/2}$  and the modulus of smoothness of  $\mathcal{B}$  is expressed as

$$\rho_{\mathcal{B}}(t) = \sup\left\{\frac{\|e_1 + e_2\| + \|e_1 - e_2\|}{2} - 1 : \|e_1\| \le 1, \|e_2\| \le t\right\}.$$

The Hausdorff metric  $\mathcal{D}(\cdot, \cdot)$  on  $CB(\mathcal{B})$  is expressed as

$$\mathcal{D}(\varphi,\psi) = \max\left\{\sup_{e_1 \in \varphi} \inf_{e_2 \in \psi} d(e_1,e_2), \sup_{e_2 \in \psi} \inf_{e_1 \in \varphi} d(e_1,e_2)\right\}.$$

Now onward, the Banach space  $\mathcal{B}$  is taken as a uniformly smooth. Let  $\Omega \neq \phi$  be a closed convex subset of  $\mathcal{B}$ . A mapping  $R_{\Omega} : \mathcal{B} \to \Omega$  is retraction if  $R_{\Omega}^2 = R_{\Omega}$ , nonexpansive retraction if  $R_{\Omega}$  is retraction and  $||R_{\Omega}(e_1) - R_{\Omega}(e_2)|| \le ||e_1 - e_2||, \forall e_{12}, e_2 \in \mathcal{B}$ ; and sunny retraction if  $R_{\Omega}(R_{\Omega}e_1 - t(e_1 - R_{\Omega}e_1)) = R_{\Omega}e_1$ ,  $\forall e_1 \in \mathcal{B}, t \in \mathbb{R}$ . The following lemma is essential and necessary to accomplishing the goal.

**Lemma 3.** A mapping  $R_{\Omega} : \mathcal{B} \to \Omega$  is sunny nonexpansive retraction if and only if

$$\langle e_1 - R_\Omega(e_1), J(R_\Omega(e_1) - e_2) \rangle \ge 0, \forall e_1 \in \mathcal{B}, e_2 \in \Omega(e_1)$$

Assumption C [40] For given  $e_1, e_2, \varsigma^* \in \mathcal{B}$  and constant  $\kappa > 0$ , the mapping  $P_{\Omega}$  fulfills the condition

$$\|P_{\Omega(e_1)}(\varsigma^*) - P_{\Omega(e_2)}(\varsigma^*)\| \le \kappa \|e_1 - e_2\|.$$

**Definition 1.** A mapping  $\varphi : \mathcal{B} \to \mathcal{B}$  is referred as

(*i*)  $\eta$ -strongly accretive, if  $\exists \eta \geq 0$ ,

$$\langle \varphi(e_1) - \varphi(e_2), J(e_1 - e_2) \rangle \ge \eta ||e_1 - e_2||^2, \forall e_1, e_2 \in \mathcal{B};$$

(*ii*)  $\delta$ -*Lipschitz continuous*, *if*  $\exists \delta > 0$ ,

$$\|\varphi(e_1) - \varphi(e_2)\| \le \delta \|e_1 - e_2\|, \forall e_1, e_2 \in \mathcal{B},$$

(*iii*)  $\kappa$ -expanding if,  $\exists \kappa > 0$ ,

 $\|\varphi(e_1) - \varphi(e_2)\| \ge \kappa \|e_1 - e_2\|, \forall e_1, e_2 \in \mathcal{B}.$ 

Note that  $\eta$ -strongly accretive mapping  $\varphi$  is  $\eta$ -expanding.

**Definition 2.** Let  $\varphi$ ,  $S, T : \mathcal{B} \to \mathcal{B}; \psi : \mathcal{B} \times \mathcal{B} \to \mathcal{B}$  be the single-valued mappings. Then  $\psi(S, T)$  is referred as

(*i*)  $\tau$ -strongly accretive regarding  $\varphi$ , if  $\exists \tau \geq 0$ ,

$$\langle \psi(S(e_1), T(e_1)) - \psi(S(e_2), T(e_2)), J(\varphi(e_1) - \varphi(e_2)) \geq \tau ||e_1 - e_2||^2, \forall e_1, e_2 \in \mathcal{B};$$

(*ii*)  $\varsigma$ -Lipschitz continuous, if  $\exists \varsigma > 0$ ,

$$\|\psi(S(e_1), T(e_1)) - \psi(S(e_2), T(e_2))\| \le \varsigma \|e_1 - e_2\|, \forall e_1, e_2 \in \mathcal{B}.$$

**Definition 3.** A mapping  $\psi : \mathcal{B} \times \mathcal{B} \to \mathcal{B}$  is called  $(\sigma, v)$ -mixed Lipschitz continuous, if for some  $\sigma, v > 0$ ,

$$\|\psi(e_1,t_1) - \psi(e_2,t_2)\| \le \sigma \|e_1 - e_2\| + \nu \|t_1 - t_2\|, \forall e_1, e_2, t_1, t_2 \in \mathcal{B}.$$

**Remark 1.** Let  $A : \mathcal{B} \to CB(\mathcal{B})$  be a set-valued mapping, then for every  $\hat{a}, \hat{b} \in \mathcal{B}$  and  $\mu \in A(e_1), \upsilon \in B(e_2)$  there exist  $\epsilon, \delta > 0$  such that

- (i)  $\|\mu \nu\| \le \mathcal{D}(A(e_1), A(e_2)) + \epsilon \|e_1 e_2\|,$
- (*ii*)  $\|\mu \nu\| \leq \delta \mathcal{D}(A(e_1), A(e_2)).$

**Lemma 4.** [30] Suppose that the nonnegative real sequences  $\{\hat{a}_n\}$  and  $\{\hat{b}_n\}$  satisfy

$$\hat{a}_{n+1} \le \tau \hat{a}_n + \hat{b}_n, \forall n \in \mathbb{N},$$

for some  $0 \le \tau < 1$ . If  $\lim_{n \to \infty} \hat{b}_n = 0$ , then  $\lim_{n \to \infty} \hat{a}_n = 0$ ,

Next, we shall define  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ . Let  $A, B : \mathcal{B} \to CB(\mathcal{B})$  be set-valued mappings,  $\Psi, \psi : \mathcal{B} \times \mathcal{B} \to \mathcal{B}, \varphi, S, T : \mathcal{B} \to \mathcal{B}$  be single-valued mappings, and for any  $\hat{a} \in \mathcal{B}, \Omega : \mathcal{B} \to 2^{\mathcal{B}}$  assigns a closed convex-valued set  $\Omega(\hat{a})$  in  $\mathcal{B}$ . We are intended to examine the extended quasi variational inequality  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$  which is to find  $\{(\hat{a}, \mu, \upsilon) : \hat{a} \in \mathcal{B}, \varphi(\hat{a}) \in \Omega(\hat{a}), \nu \in B(\hat{a})\}$  such that

$$\langle \rho(\psi(S(\hat{a}), T(\hat{a})) + \varphi(\hat{a})) - \Psi(\mu, \nu), J(\varphi(\hat{b}) - \varphi(\hat{a})) \rangle \ge 0, \forall \hat{b} \in \mathcal{B}, \varphi(\hat{b}) \in \Omega(\hat{a}).$$
(9)

 $EQVI(\mathcal{B},\psi,\varphi,\Psi)$  is a broader and unified class of quasi variational inequality. Several VIs and QVIs can be achieved by  $EQVI(\mathcal{B},\psi,\varphi,\Psi)$  for different selection of involved mappings. In the next result, we obtain an equivalent fixed point problem by transforming  $(EQVI(\mathcal{B},\psi,\varphi,\Psi))$ .

**Lemma 5.** Let  $P_{\Omega(\hat{a})} : \mathcal{B} \to \Omega(\hat{a})$  be a sunny nonexpansive retraction. An element  $(\hat{a}, \mu, \nu)$  with  $\hat{a} \in \mathcal{B}, \varphi(\hat{a}) \in \Omega, \mu \in A(\hat{a}), \nu \in B(\hat{a})$  solves  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$  if and only if  $\hat{a} \in Fix(Q)$ , where

$$Q(\hat{a}) = \hat{a} - \varphi(\hat{a}) + P_{\Omega(\hat{a})}[(1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)],$$
(10)

and  $\rho > 0$  is a constant.

**Theorem 1.** Suppose that  $\varphi : \mathcal{B} \to \mathcal{B}$  be  $\kappa$ -strongly accretive,  $\delta$ -Lipschitz continuous mapping;  $\Psi, \psi : \mathcal{B} \times \mathcal{B} \to \mathcal{B}$  and  $S, T : \mathcal{B} \to \mathcal{B}$  be the single-valued mappings so that  $\psi(S, T)$  is  $\tau$ -strongly accretive regarding  $\varphi$  and  $\varsigma$ -Lipschitz continuous,  $\Psi$  is  $(\sigma, \upsilon)$ -mixed Lipschitz continuous and  $A, B : \mathcal{B} \to CB(\mathcal{B})$  be  $\theta$ - $\mathcal{D}$ -Lipschitz continuous,  $\vartheta$ - $\mathcal{D}$ -Lipschitz continuous, respectively. If the retraction  $P_{\Omega(\hat{a})} : \mathcal{B} \to \Omega(\hat{a})$  comply with the Assumption C and constant  $\rho > 0$  satisfies:

$$\Theta + \rho\delta < 1 - \Phi, \kappa < \frac{1 + 64\varepsilon\delta^2}{2}, \tau < \frac{\delta^2 + 64\varepsilon\varsigma^2}{2\rho}.$$
(11)

Then  $(\hat{a}, \mu, \nu)$  such that  $\hat{a} \in \mathcal{B}, \varphi(\hat{a}) \in \Omega(\hat{a}), \mu \in A(\hat{a}), \nu \in B(\hat{a})$  solves  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ .

*Proof.* Assume that for given  $\hat{a}, \hat{b} \in \mathcal{B}, \mu \in A(\hat{a}), \nu \in B(\hat{a}), \bar{\mu} \in A(\hat{b}), \bar{\nu} \in B(\hat{b})$ , there exist  $a^* \in Q(\hat{a})$  and  $b^* \in Q(\hat{b})$  so that

$$a^* = \hat{a} - \varphi(\hat{a}) + P_{\Omega(\hat{a})}[(1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)],$$
(12)

and

$$b^{*} = \hat{b} - \varphi(\hat{b}) + P_{\Omega(\hat{b})}[(1-\rho)\varphi(\hat{b}) - \rho\psi(S(\hat{b}), T(\hat{b})) + \Psi(\bar{\mu}, \bar{\nu})].$$
(13)

71

## By (12), (13) and considering the Assumption C, we obtain

$$\begin{split} \|a^{*} - b^{*}\| &\leq \|\hat{a} - \hat{b} - (\varphi(\hat{a}) - \varphi(\hat{b}))\| \\ &+ \|P_{\Omega(\hat{a})}[(1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)] \\ &- P_{\Omega(\hat{b})}[(1 - \rho)\varphi(\hat{b}) - \rho\psi(S(\hat{b}), T(\hat{b})) + \Psi(\bar{\mu}, \bar{\nu})]\| \\ &\leq \|\hat{a} - \hat{b} - (\varphi(\hat{a}) - \varphi(\hat{b}))\| + \xi \|\hat{a} - \hat{b}\| \\ &+ \|(1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu) \\ &- [(1 - \rho)\varphi(\hat{b}) - \rho\psi(S(\hat{b}), T(\hat{b})) + \Psi(\bar{\mu}, \bar{\nu})]\| \\ &\leq \|\hat{a} - \hat{b} - (\varphi(\hat{a}) - \varphi(\hat{b}))\| + \xi \|\hat{a} - \hat{b}\| + \rho \|\varphi(\hat{a}) - \varphi(\hat{b})\| \\ &+ \|\varphi(\hat{a}) - \varphi(\hat{b}) - \rho(\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b})))\| \\ &+ \|\Psi(\mu, \nu) - \Psi(\bar{\mu}, \bar{\nu})\|. \end{split}$$

Employing  $\kappa$ -strongly accretive property,  $\delta$ -Lipschitz continuity of  $\varphi$  and taking advantage of Lemma 2, we achieve

$$\begin{aligned} \|\hat{a} - \hat{b} - (\varphi(\hat{a}) - \varphi(\hat{b}))\|^{2} \\ &\leq \|\hat{a} - \hat{b}\|^{2} - 2\langle\varphi(\hat{a}) - \varphi(\hat{b}), J(\hat{a} - \hat{b} - (\varphi(\hat{a}) - \varphi(\hat{b})))\rangle \\ &\leq \|\hat{a} - \hat{b}\|^{2} - 2\langle\varphi(\hat{a}) - \varphi(\hat{b}), J(\hat{a} - \hat{b})\rangle \\ &+ 2\langle\varphi(\hat{a}) - \varphi(\hat{b}), J(\hat{a} - \hat{b} - (\varphi(\hat{a}) - \varphi(\hat{b}))) - J(\hat{a} - \hat{b})\rangle \\ &\leq (1 - 2\kappa + 64\varepsilon\delta^{2})\|\hat{a} - \hat{b}\|^{2}. \end{aligned}$$
(15)

Recalling the Lemma 2 and assumptions that  $\varphi$  is  $\delta$ -Lipschitz continuous,  $\psi(S,T)$  is  $\tau$ -strongly accretive regarding  $\varphi$  and  $\varsigma$ -Lipschitz continuous, we achieve

$$\begin{aligned} \|\varphi(\hat{a}) - \varphi(\hat{b}) - \rho(\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b})))\|^{2} \\ &\leq \|\varphi(\hat{a}) - \varphi(\hat{b})\|^{2} - 2\rho\langle\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b})), \\ J(\varphi(\hat{a}) - \varphi(\hat{b}) - \rho(\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b})))\rangle \\ &\leq \|\varphi(\hat{a}) - \varphi(\hat{b})\|^{2} - 2\rho\langle\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b}))), \\ J(\varphi(\hat{a}) - \varphi(\hat{b}))\rangle + 2\rho\langle\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b}))), \\ J(\varphi(\hat{a}) - \varphi(\hat{b}) - \rho(\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b})))) \\ &- J(\varphi(\hat{a}) - \varphi(\hat{b}))\rangle \\ &\leq \delta^{2} \|\hat{a} - \hat{b}\|^{2} - 2\rho\tau \|\hat{a} - \hat{b}\|^{2} + 64\varepsilon\varsigma^{2} \|\hat{a} - \hat{b}\|^{2} \\ &= (\delta^{2} - 2\rho\tau + 64\varepsilon\varsigma^{2})\|\hat{a} - \hat{b}\|^{2}. \end{aligned}$$

Employing  $(\sigma, v)$ -mixed Lipschitz continuity of  $\Psi$ , Lipschitz continuities of A and B yields

$$\begin{aligned} \|\Psi(\mu,\nu) - \Psi(\bar{\mu},\bar{\nu})\| &\leq \sigma \|\mu - \bar{\mu}\| + \nu \|\nu - \bar{\nu}\| \\ &\leq \sigma \mathcal{D}(A(\hat{a}), A(\hat{b})) + \nu \mathcal{D}(B(\hat{a}), B(\hat{b})) \\ &\leq \sigma \theta \|\hat{a} - \hat{b}\| + \nu \vartheta \|\hat{a} - \hat{b}\| \\ &= (\sigma \theta + \nu \vartheta) \|\hat{a} - \hat{b}\|. \end{aligned}$$
(17)

Combining (15), (16) and (17), (14) turns into

$$||a^* - b^*|| \le \{\sqrt{1 - 2\kappa + 64\varepsilon\delta^2} + (\xi + \rho\delta) + \sqrt{\delta^2 - 2\rho\tau + 64\varepsilon\varsigma^2} + (\sigma\theta + \upsilon\theta)\}||\hat{a} - \hat{b}||$$

$$= (\Theta + \rho\delta + \Phi)||\hat{a} - \hat{b}|| = L||\hat{a} - \hat{b}||,$$
(18)

where,

$$L = \Theta + \rho\delta + \Phi, \Theta = \sqrt{1 - 2\kappa + 64\varepsilon\delta^2} + \sigma\theta + \upsilon\vartheta, \Phi = \xi + \sqrt{\delta^2 - 2\rho\tau + 64\varepsilon\varsigma^2}.$$
(19)

Clearly, from (18) and condition (11), we conclude that the set-valued mapping Q is a contraction and hence  $\exists \hat{a} \in \mathcal{B}$  so that  $\hat{a} \in Fix(Q)$ . Thus, Lemma 5 guarantees that  $(\hat{a}, \mu, \nu)$  so that  $\hat{a} \in \mathcal{B}, \mu \in A(\hat{a}), \nu \in B(\hat{a})$  solves  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ .

**Example 1.** Consider a real Banach space  $l_2 = \{\hat{a} = (\hat{a}_0, \hat{a}_1, \hat{a}_2, \cdots) : \sum_{n=0}^{\infty} |\hat{a}_n|^2 < \infty, \hat{a}_n \in \mathbb{R}, \forall n = 0, 1, 2, \cdots \}$  and  $||\hat{a}||_2 = \left(\sum_{n=0}^{\infty} |\hat{a}_n|^2\right)^{1/2}$ . Define  $\varphi, S, T : \mathcal{B} \to \mathcal{B}; \psi, \Psi : \mathcal{B} \times \mathcal{B} \to \mathcal{B}$  and  $A, B : \mathcal{B} \to CB(\mathcal{B})$  by

$$\varphi(\hat{a}) = \frac{\hat{a}}{2}, S(\hat{a}) = \frac{\hat{a}}{4}, T(\hat{a}) = \frac{\hat{a}}{8}, \forall \hat{a} \in \mathcal{B},$$
$$\psi(S(\hat{a}), T(\hat{a})) = \frac{(S(\hat{a}) + T(\hat{a}))}{4}, \Psi(\mu, \nu) = \frac{\mu + \nu}{8}$$
and  $A(\hat{a}) = \left\{\frac{\hat{a}}{4}\right\}, \quad B(\hat{a}) = \left\{\frac{2\hat{a}}{3}\right\}.$ 

Then, one can discern that for all  $\hat{a}, \hat{b} \in \mathcal{B}$ ,

$$\begin{split} \langle \hat{a} - \hat{b}, \varphi(\hat{a}) - \varphi(\hat{b}) \rangle &= \langle \hat{a} - \hat{b}, \frac{\hat{a}}{2} - \frac{\hat{b}}{2} \rangle = \frac{1}{2} ||\hat{a} - \hat{b}||_2^2, \\ ||\varphi(\hat{a}) - \varphi(\hat{b})||_2 &= ||\frac{1}{2}\hat{a} - \frac{1}{2}\hat{b}||_2 = \frac{1}{2} ||\hat{a} - \hat{b}||_2. \end{split}$$

*i.e.*,  $\varphi$  *is*  $\frac{1}{2}$ *-strongly accretive and*  $\frac{1}{2}$ *-Lipschitz continuous. Also,* 

$$\langle \psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b})), \varphi(\hat{a}) - \varphi(\hat{b}) \rangle = \langle \frac{3\hat{a}}{32} - \frac{3\hat{b}}{32}, \frac{\hat{a}}{2} - \frac{\hat{b}}{2} \rangle = \frac{3}{64} ||\hat{a} - \hat{b}||_2^2$$

$$\|\psi(S(\hat{a}), T(\hat{a})) - \psi(S(\hat{b}), T(\hat{b}))\|_2 = \left\|\frac{3\hat{a}}{32} - \frac{3\hat{b}}{32}\right\|_2 = \frac{3}{32}\|\hat{a} - \hat{b}\|_2.$$

*i.e.*,  $\psi(S,T)$  is  $\frac{3}{64}$ -strongly accretive and  $\frac{3}{32}$ -Lipschitz continuous. Now, for all  $\mu \in A(\hat{a}), \bar{\mu} \in A(\hat{b}), v \in B(\hat{a}), \bar{v} \in B(\hat{b})$ , one can acquire

$$\|\Psi(\mu,\nu) - \Psi(\bar{\mu},\bar{\nu})\|_{2} = \left\|\frac{\mu+\nu}{4} - \frac{\bar{\mu}+\bar{\nu}}{4}\right\|_{2} \le \frac{1}{4}\|\mu-\bar{\mu}\|_{2} + \frac{1}{4}\|\nu-\bar{\nu}\|_{2},$$

$$\|\mu - \bar{\mu}\|_2 = \|\frac{\hat{a}}{4} - \frac{\hat{b}}{4}\|_2 = \frac{1}{4}\|\hat{a} - \hat{b}\|_2 \text{ and } \|\nu - \bar{\nu}\|_2 = \|\frac{2\hat{a}}{3} - \frac{2\hat{b}}{3}\|_2 = \frac{2}{3}\|\hat{a} - \hat{b}\|_2$$

Thus,  $\Psi$  is  $(\frac{1}{4}, \frac{1}{4})$ -mixed Lipschitz continuous, A and B are  $\frac{1}{4}$  and  $\frac{2}{3}$ -Lipschitz continuous, respectively. Define  $\Omega : \mathcal{B} \to \mathcal{B}$  by

$$\Omega(\hat{a}) = \Omega(\{\hat{a}_n\}) = \left\{ t = \{t_n\} : t_0 \ge \frac{\hat{a}_0}{15}, t_n = 0, \forall n \in \mathbb{N} \right\}.$$

We assert that  $\Omega(\hat{a})$  is a closed and convex. For arbitrary  $\alpha \in [0,1]$  and  $t_0, m_0 \in \Omega(\hat{a})$ , we have  $\alpha t_0 + (1-\alpha)m_0 \ge \frac{\hat{a}_0}{15}$  and hence  $\Omega(\hat{a})$  is a convex set. Define  $f : [\frac{\hat{a}_0}{15}, \infty) \to \Omega(\hat{a})$  by  $f(r) = (r, 0, 0, \cdots)$ . Evidently, f is well defined. For  $t \neq m \in [\frac{\hat{a}_0}{15}, \infty)$ , we achieve  $(t, 0, 0, \cdots) \neq (m, 0, 0, \cdots)$ , i.e., f is one-to-one. Simple observation reveals that there is an  $t_0 \in [\frac{\hat{a}_0}{15}, \infty)$  so that  $f(t_0) = (t_0, 0, 0, \cdots)$  for each  $t = (t_0, 0, 0, \cdots) \in \Omega(\hat{a})$ , i.e., f is onto. Let  $(l_2, d')$  and  $(\mathbb{R}, d)$  be usual metric spaces. For each  $t, m \in [\frac{\hat{a}_0}{15}, \infty)$ , we obtain

$$d'(f(t), f(m)) = d'((t, 0, 0, \dots), (m, 0, 0, \dots)) = |t - m| = d(t, m).$$

Thus f is continuous. Additionally,  $f^{-1}$  is also continuous and bijective, so f is homeomorphism. So  $\Omega(\hat{a})$  is homeomorphic to a closed set  $[\frac{\hat{a}_0}{15}, \infty)$ , hence  $\Omega(\hat{a})$  is closed. Define retraction  $P_{\Omega(\hat{a})} : \mathcal{B} \to \Omega(\hat{a})$  by

$$P_{\Omega(\hat{a})}(l_0, l_1, l_2, \cdots) = \begin{cases} (l_0, l_1, l_2, \cdots), & \text{if } (l_0, l_1, l_2, \cdots) \in \Omega(\hat{a}) \\ (\frac{\hat{a}_0}{15}, 0, 0, \cdots), & \text{if } (l_0, l_1, l_2, \cdots) \notin \Omega(\hat{a}), l_0 < \frac{\hat{a}_0}{15} \\ (l_0, 0, 0, \cdots), & \text{if } (l_0, l_1, l_2, \cdots) \notin \Omega(\hat{a}), l_0 \ge \frac{\hat{a}_0}{15} \end{cases}$$

In order to demonstrate that  $P_{\Omega(\hat{a})}$  complies with assumption *C*, we address the subsequent cases. Case (a). For arbitrary  $\hat{a} = \{\hat{a}_n\}, q = \{q_n\}, l = \{l_n\} \in \mathcal{H}$ , assume that  $\hat{a}_0 \leq q_0$ . 1. If  $l = \{l_n\} \in \Omega(q)$ , then  $l = \{l_n\} \in \Omega(\hat{a})$  and hence

$$\begin{split} \|P_{\Omega(\hat{a})}(l) - P_{\Omega(q)}(l)\|_2 &= \|(l_0, l_1, l_2, \cdots) - (l_0, l_1, l_2, \cdots)\|_2 \\ &= 0 \le \frac{1}{15} \|\hat{a} - q\|_2. \end{split}$$

2. If  $l = (l_0, l_1, l_2, \dots) \notin \Omega(q)$  and  $l = (l_0, l_1, l_2, \dots) \in \Omega(\hat{a})$ , then either  $l_0 < \frac{q_0}{15}$  or  $l_0 \ge \frac{q_0}{15}$ . For  $l_0 < \frac{q_0}{15}$ , we have

$$\begin{split} \|P_{\Omega(\hat{a})}(l) - P_{\Omega(q)}(l)\|_2 &= \|(l_0, l_1, l_2, \cdots) - \left(\frac{\hat{a}_0}{15}, 0, 0, \cdots\right)\|_2 \\ &= \|(l_0, 0, 0, \cdots) - \left(\frac{\hat{a}_0}{15}, 0, 0, \cdots\right)\|_2 \\ &= \left|l_0 - \frac{\hat{a}_0}{15}\right| = l_0 - \frac{\hat{a}_0}{15} \\ &\leq \frac{1}{15} \|\hat{a} - q\|_2. \end{split}$$

For  $l_0 \geq \frac{q_0}{15}$ , we have

$$\begin{split} \|P_{\Omega(\hat{a})}(l) - P_{\Omega(q)}(l)\|_{2} &= \|(l_{0}, l_{1}, l_{2}, \cdots) - (l_{0}, 0, 0, \cdots)\|_{2} \\ &= \|(l_{0}, 0, 0, \cdots) - (l_{0}, 0, 0, \cdots)\|_{2} \\ &= 0 \le \frac{1}{15} \|\hat{a} - q\|_{2}. \end{split}$$

3. If  $l = (l_0, l_1, l_2, \dots) \notin \Omega(q)$  and  $l = (l_0, l_1, l_2, \dots) \notin \Omega(\hat{a})$ , then either  $l_0 < \frac{q_0}{15}$  or  $l_0 \ge \frac{q_0}{15}$  and  $l_0 < \frac{\hat{a}_0}{15}$  or  $l_0 \ge \frac{\hat{a}_0}{15}$ . For  $l_0 < \frac{\hat{a}_0}{15}$ , we have  $l_0 < \frac{q_0}{15}$ . Thus,

$$\begin{split} \|P_{\Omega(p)}(l) - P_{\Omega(q)}(l)\|_2 &= \left\| \left( \frac{\hat{a}_0}{15}, 0, 0, \cdots \right) - \left( \frac{q_0}{15}, 0, 0, \cdots \right) \right\|_2 \\ &= \left| \frac{\hat{a}_0}{15} - \frac{q_0}{15} \right| \le \frac{1}{15} \|\hat{a} - q\|_2. \end{split}$$

For  $l_0 \geq \frac{\hat{a}_0}{15}$  and  $l_0 \geq \frac{q_0}{15}$ , we have

$$\begin{split} \|P_{\Omega(\hat{a})}(l) - P_{\Omega(q)}(l)\|_2 &= \|(l_0, 0, 0, \cdots) - (l_0, 0, 0, \cdots)\|_2 \\ &= 0 \le \frac{1}{15} \|\hat{a} - q\|_2. \end{split}$$

For  $l_0 \geq \frac{\hat{a}_0}{15}$  and  $l_0 < \frac{q_0}{15}$ , we have

$$\begin{aligned} \|P_{\Omega(p)}(l) - P_{\Omega(q)}(l)\|_{2} &= \|(l_{0}, 0, 0, \cdots) - \left(\frac{q_{0}}{10}, 0, 0, \cdots)\|_{2} \\ &= \left|l_{0} - \frac{q_{0}}{15}\right| = \frac{q_{0}}{15} - l_{0} \le \frac{q_{0}}{15} - \frac{\hat{a}_{0}}{15} \le \frac{1}{15} \|\hat{a} - q\|_{2} \end{aligned}$$

*Case* (b). Analogously, for  $\hat{a} = \{\hat{a}_n\}, q = \{q_n\}, r = \{l_n\} \in \mathcal{B}$  with  $\hat{a}_0 > q_0$ , we can verify that

$$||P_{\Omega(\hat{a})}(l) - P_{\Omega(q)}(l)||_2 \le \frac{1}{15} ||\hat{a} - q||_2.$$

Thus,  $P_{\Omega(\hat{a})}$  satisfies the assumption C with constant  $\xi = \frac{1}{15}$ . Further, for  $\rho = \frac{1}{2}$  and  $\varepsilon = 10^{-2}$ , the condition (11) is also satisfied for  $\kappa = \delta = \frac{1}{2}$ ,  $\tau = \frac{3}{64}$ ,  $\varsigma = \frac{3}{32}$ ,  $\sigma = \upsilon = \frac{1}{4}$ ,  $\theta = \frac{1}{4}$ ,  $\theta = \frac{2}{3}$ . Finally, consider  $\hat{a}^* = (\hat{a}_0^*, 0, 0, \cdots) : \hat{a}_0^* \ge 0$ , then for  $\hat{a}^* > 0$ , we have

$$\begin{split} \langle \rho(\psi(S(\hat{a}), T(\hat{a})) + \varphi(\hat{a})) - \Psi(u, v), J(\varphi(\hat{b}) - \varphi(\hat{a})) \rangle &= \langle \frac{35}{192} \hat{a}, \frac{1}{2} (\hat{b}) - \frac{1}{2} (\hat{a}) \rangle \\ &= \frac{35}{3384} \langle (\hat{a}_0, 0, 0, \cdots), (\hat{b}_0 - \hat{a}_0, 0, 0, \cdots) \rangle \\ &< 0, \forall \hat{b} = (\hat{b}_0, 0, 0, \cdots) \in \Omega(\hat{a}). \end{split}$$

However, for  $\hat{a} = (0, 0, 0, \cdots)$ , we have

$$\begin{aligned} \langle \rho(\psi(S(\hat{a}), T(\hat{a})) + \varphi(\hat{a})) - \Psi(u, v), J(\varphi(\hat{b}) - \varphi(\hat{a})) \rangle \\ &= \langle (0, 0, 0, \cdots), (\hat{b}_0 - \hat{a}_0, 0, 0, \cdots) \rangle \end{aligned}$$

$$= 0, \forall \hat{b} = (\hat{b}_0, 0, 0, \cdots) \in \Omega(\hat{a}).$$

Hence,  $(\hat{a}, \mu, \nu) = (0, 0, 0)$  is a unique solution of  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ .

#### 3. ITERATIVE SCHEME AND CONVERGENCE

Next, we discuss the lemma below in Banach spaces plays a pivotal role in establishing the convergence. An identical form proved in Hilbert spaces can be found in [13].

**Lemma 6.** Under the suppositions of the Theorem 1, the sequence  $\{\Xi_n || \hat{a}_n - \hat{a}_{n-1} ||\}$  converges to 0, where  $\Xi_n$  is outlined below:

$$\Xi_{n} = \begin{cases} \min\{\frac{n-1}{n-1+\kappa}, \frac{e_{n}}{\|\hat{a}_{n}-\hat{a}_{n-1}\|}\}, & \text{if } \hat{a}_{n} \neq \hat{a}_{n-1}, \\ \frac{n-1}{n-1+\kappa}, & \text{if } \hat{a}_{n} = \hat{a}_{n-1}, \end{cases}$$
(20)

 $\forall n \in \mathbb{N}, \kappa \geq 3 \text{ and } e_n \in (0, \infty) \text{ with } \lim_{n \to \infty} e_n = 0.$ 

*Proof.* The proof can be justified by taking the following possibilities into consideration. Case (c<sub>1</sub>). If  $\hat{a}_n = \hat{a}_{n-1}$ , then naturally  $\{\Xi_n || \hat{a}_n - \hat{a}_{n-1} ||\}$  is zero sequence. Next, we carry on for  $\hat{a}_n \neq \hat{a}_{n-1}$ .

Case (c<sub>1</sub>). If  $a_n = a_{n-1}$ , then naturally  $\{\Xi_n \| \hat{a}_n - \hat{a}_{n-1} \|\}$  is zero sequence  $Case (c_2)$ . Suppose  $\Xi_n = \frac{n-1}{n-1+\kappa}$ ,  $\forall n \in \mathbb{N}$ , then  $0 \le \Xi_n = \frac{n-1}{n-1+\kappa} \le \frac{e_n}{\|\hat{a}_n - \hat{a}_{n-1}\|}$  and hence  $0 \le \Xi_n \|\hat{a}_n - \hat{a}_{n-1}\| \le e_n$ .  $Case (c_3)$ . Suppose  $\Xi_n = \frac{e_n}{\|\hat{a}_n - \hat{a}_{n-1}\|}$ ,  $\forall n \in \mathbb{N}$ , then  $0 \le \Xi_n = \frac{e_n}{\|\hat{a}_n - \hat{a}_{n-1}\|} \le \frac{n-1}{n-1+\kappa}$  and hence  $0 \le \Xi_n \|\hat{a}_n - \hat{a}_{n-1}\| = e_n$ .  $Case (c_4)$ . Finally, we have  $\Xi_n = \frac{n-1}{n-1+\kappa}$ .

Case (c<sub>4</sub>). Finally, suppose  $\Xi_n = \frac{n-1}{n-1+\kappa} = \frac{e_n}{\|\hat{a}_n - \hat{a}_{n-1}\|}$  for some  $n \in \mathbb{N}$ , then we obtain  $0 \le \Xi_n \|\hat{a}_n - \hat{a}_{n-1}\| = e_n$ . Thus, in all cases,  $0 \le \Xi_n \|\hat{a}_n - \hat{a}_{n-1}\| \le e_n$ . Since  $\lim_{n \to \infty} e_n = 0$  and hence  $\{\Xi_n \| \hat{a}_n - \hat{a}_{n-1} \|\}$  converges to 0.

We reformat the algorithm (8) as follows in light of (10).

**Algorithm 1.** Initialization: Given  $\rho > 0$ , initial points  $\hat{a}_0, \hat{a}_1 \in \mathcal{B}, \mu_0 \in A(\hat{a}_0), \nu_0 \in B(\hat{a}_0)$ . Choose the sequences  $\{\alpha_n\}_{n=1}^{\infty}, \{\beta_n\}_{n=1}^{\infty}, \{\gamma_n\}_{n=1}^{\infty}, \{\tau_n\}_{n=1}^{\infty}$  and  $\{e_n\}_{n=1}^{\infty}$  so that the assumptions of Lemma 6 hold. Step 1: For given iterates  $\hat{a}_{n-1}, \hat{a}_n$ , choose  $\Xi_n$  so that

$$\Xi_n = \begin{cases} \min\{\frac{n-1}{n-1+\kappa}, \frac{e_n}{\|\hat{a}_n - \hat{a}_{n-1}\|}\}, & \text{if } \hat{a}_n \neq \hat{a}_{n-1}, \\ \frac{n-1}{n-1+\kappa}, & \text{if } \hat{a}_n = \hat{a}_{n-1}. \end{cases}$$

Step 2: Set

$$\begin{cases} \hat{c}_n = \hat{a}_n + \gamma_n (\hat{a}_n - \hat{a}_{n-1}), \\ \hat{b}_n = \hat{a}_n + \tau_n (\hat{a}_n - \hat{a}_{n-1}). \end{cases}$$

Compute  $\zeta_n = (1-\rho)\varphi(\hat{b}_n) - \rho\psi(S(\hat{b}_n), T(\hat{b}_n)) + \Psi(\bar{\mu}_n, \bar{\nu}_n)] : \bar{\mu}_n \in A(\hat{b}_n), \bar{\nu}_n) \in B(\hat{b}_n).$ Step 3: Compute  $\hat{a}_{n+1} = (1-\gamma_n - \tau_n)\hat{b}_n + \gamma_n\{\hat{b}_n - \varphi(\hat{b}_n) + P_{\Omega(\hat{b}_n)}\zeta_n\} + \tau_n\hat{c}_n.$ Set n := n+1 and go to Step 1.

**Theorem 2.** Suppose that all the hypotheses of Theorem 1 are fulfilled by the mappings  $P_{\Omega(\hat{\alpha})}, \varphi, \Psi, \psi, S, T, A$  and B. Suppose that  $\{\hat{a}_n\}_{n=1}^{\infty}$  is generated by Algorithm 1 with  $\max\{|\gamma_n|, |\tau_n|\} \leq \Xi_n, \forall n \in \mathbb{N}$ , where  $\Xi_n$  is the updating parameter described in (20). Let  $\{\alpha_n\}_{n=1}^{\infty}, \{\beta_n\}_{n=1}^{\infty}$  and  $\{e_n\}_{n=1}^{\infty}$  are sequences in (0, 1), so that  $0 < \alpha_n + \beta_n < 1, \alpha \leq \alpha_n$  for some  $\alpha > 0$  and  $\lim_{n \to \infty} e_n = 0, \forall n \in \mathbb{N}$ . Then  $\hat{a}_n \to \hat{a}, \mu_n \to \mu$  and  $\nu_n \to \nu$  and  $(\hat{a}, \mu, \nu)$  solves  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ . *Proof.* It is evident by the Theorem 1 that  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$  admits a solution  $(\hat{a}, \mu, \nu)$  such that  $\hat{a} \in \mathcal{B}, \varphi(\hat{a}) \in \Omega(\hat{a}), \mu \in A(\hat{a})$  and  $\nu \in B(\hat{a})$ . Then

$$\hat{a} = \hat{a} - \varphi(\hat{a}) + P_{\Omega(\hat{a})}[(1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)].$$
(21)

Next, we substantiate that  $\hat{a}_n \rightarrow \hat{a}$  an  $n \rightarrow \infty$ . Using the presumptions from Theorem 1, Assumption C, utilizing Lemma 2 and replicating the steps as from (15)-(18), we acquire

$$\begin{aligned} \|\hat{b}_{n} - \varphi(\hat{b}_{n}) + P_{\Omega(\hat{b}_{n})}\zeta_{n} - \hat{a}\| \\ &\leq \|\hat{b}_{n} - \hat{a} - (\varphi(\hat{b}_{n}) - \varphi(\hat{a}))\| + \xi \|\hat{b}_{n} - \hat{a}\| + \rho \|\varphi(\hat{b}_{n}) - \varphi(\hat{a})\| \\ &+ \|\varphi(\hat{b}_{n}) - \varphi(\hat{a}) - \rho(\psi(S(\hat{b}_{n}), T(\hat{b}_{n})) - \psi(S(\hat{a}), T(\hat{a})))\| \\ &+ \|\Psi(\bar{\mu}_{n}, \bar{\nu}_{n}) - \Psi(\mu, \nu)\| \\ &\leq [\sqrt{1 - 2\kappa + 64\varepsilon\delta^{2}} + (\xi + \rho\delta) + \sqrt{\delta^{2} - 2\rho\tau + 64\varepsilon\varsigma^{2}} + (\sigma\theta + \upsilon\vartheta)] \|\hat{b}_{n} - \hat{a}\|, \\ &= L \|\hat{b}_{n} - \hat{a}\|, \end{aligned}$$
(22)

where, L is same as in (19). From Algorithm 1 and (22), we acquire

$$\begin{aligned} \|\hat{a}_{n+1} - \hat{a}\| &\leq (1 - \alpha_n - \beta_n) \|\hat{b}_n - \hat{a}\| + \alpha_n \|\hat{b}_n - \varphi(\hat{b}_n) \\ &+ P_{\Omega(\hat{b}_n)} \zeta_n - \hat{a}\| + \beta_n \|\hat{c}_n - \hat{a}\| \\ &\leq (1 - \alpha_n - \beta_n) \|\hat{b}_n - \hat{a}\| + \alpha_n L \|\hat{b}_n - \hat{a}\| + \beta_n \|\hat{c}_n - \hat{a}\| \\ &= (1 - \alpha_n - \beta_n + \alpha_n L) \|\hat{b}_n - \hat{a}\| + \beta_n \|\hat{c}_n - \hat{a}\|. \end{aligned}$$
(23)

Since 0 < L < 1 and  $\alpha_n \ge \alpha$ , invoking defining properties of  $\hat{b}_n$ ,  $\hat{c}_n$  and (11), (23) turns into

$$\begin{aligned} \|\hat{a}_{n+1} - \hat{a}\| &\leq (1 - \alpha_n - \beta_n + \alpha_n L) [\|\hat{a}_n - \hat{a}\| + \tau_n \|\hat{a}_n - w_{n-1}\|] \\ &+ \beta_n [\|\hat{a}_n - \hat{a}\| + \gamma_n \|\hat{a}_n - \hat{a}_{n-1}\|] \\ &\leq (1 - \alpha_n (1 - L)) \|\hat{a}_n - \hat{a}\| + [(1 - \alpha_n - \beta_n + \alpha_n L)] \tau_n | \\ &+ \beta_n |\gamma_n|] \|\hat{a}_n - \hat{a}_{n-1}\| \\ &\leq (1 - \alpha_n (1 - L)) \|\hat{a}_n - \hat{a}\| + [(1 - \alpha_n - \beta_n + \alpha_n)] \tau_n | \\ &+ \beta_n |\gamma_n|] \|\hat{a}_n - \hat{a}_{n-1}\| \\ &\leq (1 - \alpha (1 - L)) \|\hat{a}_n - \hat{a}\| + (|\tau_n| + |\gamma_n|) \|\hat{a}_n - \hat{a}_{n-1}\| \\ &\leq (1 - \alpha (1 - L)) \|\hat{a}_n - \hat{a}\| + (|\tau_n| + |\gamma_n|) \|\hat{a}_n - \hat{a}_{n-1}\| \\ &\leq (1 - \alpha (1 - L)) \|\hat{a}_n - \hat{a}\| + 2\Xi_n \|\hat{a}_n - \hat{a}_{n-1}\|. \end{aligned}$$

Invoking the Lemma 6, we acquire  $\lim_{n\to\infty} \Xi_n ||\hat{a}_n - \hat{a}_{n-1}|| = 0$  and the assumptions yield  $0 < (1 - \alpha(1 - L)) < 1$ . Thus the conclusion  $\hat{a}_n \to \hat{a}$  as  $n \to \infty$  follows by the Lemma 4. Since  $\bar{\mu}_n \in A(\hat{b}_n), \mu \in A(\hat{a})$  and A is  $\theta$ - $\mathcal{D}$ -Lipschitz continuous, then

$$\begin{aligned} \|\bar{\mu}_{n} - \mu\| &\leq \mathcal{D}(A(\hat{b}_{n}), A(\hat{a})) \leq \theta \|\hat{b}_{n} - \hat{a}\| \\ &\leq \theta [\|\hat{a}_{n} - \hat{a}\| + \tau_{n} \|\hat{a}_{n} - \hat{a}_{n-1}\|]. \end{aligned}$$
(25)

Again from Lemma 6,  $\lim_{n\to\infty} \tau_n ||\hat{a}_n - \hat{a}_{n-1}|| = 0$ . Hence,  $\lim_{n\to\infty} \overline{\mu}_n = \mu$ , and in the similar manner,  $\lim_{n\to\infty} \overline{\nu}_n = \nu$ . Also  $\{\hat{c}_n\}$  converges to  $\hat{c}$  and  $\{\hat{b}_n\}$  converges to  $\hat{b}$ . Finally, we shall demonstrate that  $\mu \in A(\hat{a}), \nu \in B(\hat{a})$ .

$$d(\mu, A(\hat{a})) \| \leq \|\mu - \mu_n\| + d(\mu_n, A(\hat{a}))$$

$$\leq \|\mu - \mu_n\| + \mathcal{D}(A(\hat{a}_n), A(\hat{a}))$$

$$\leq \|\mu - \mu_n\| + \theta \|\hat{a}_n - \hat{a}\| \to 0 \text{ as } n \to \infty.$$
(26)

Thus  $d(\mu, A(\hat{a})) = 0$ , thus  $\mu \in A(\hat{a})$  and likewise  $\nu \in B(\hat{a})$ .

# 4. EXTENDED WEINER-HOPF EQUATION

Now, we construct an extended Wiener-Hopf equation (*EWHE*) and substantiated that it is analogous to  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ . By implementing this equivalence, we derive the solution of  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ . We think about *EWHE* of finding  $\{(\hat{z}, \hat{a}, \mu, \nu) : \hat{z}, \hat{a} \in \mathcal{B}, \mu \in A(\hat{a}), \nu \in B(\hat{a})\}$  so that

$$\varphi(\hat{a}) + \rho^{-1} R_{\Omega(\hat{a})} \hat{z} = -\psi(S(\hat{a}), T(\hat{a})) + \rho^{-1} \Psi(\mu, \nu), \tag{27}$$

where  $R_{\Omega(\hat{a})} = I_d - P_{\Omega(\hat{a})}, I_d$  is the identity mapping. In the forthcoming theorem, we will correlate the solutions of EWHE(27) and  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ .

**Theorem 3.** A point  $(\hat{z}, \hat{a}, \mu, \nu)$  such that  $\hat{z}, \hat{a} \in \mathcal{B}, \mu \in A(\hat{a}), \nu \in B(\hat{a})$  solves EWHE(27) if and only if  $(\hat{a}, \mu, \nu)$  solves  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ , where

$$\varphi(\hat{a}) = P_{\Omega(\hat{a})}\hat{z},\tag{28}$$

$$\hat{z} = (1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu).$$
(29)

*Proof.* Assume that  $(\hat{z}, \hat{a}, \mu, \nu)$  such that  $\hat{z}, \hat{a} \in \mathcal{B}, \mu \in A(\hat{a}), \nu \in B(\hat{a})$  is a solution of EWHE(27). Then, one can discern that

$$\rho\varphi(\hat{a}) + \rho\psi(S(\hat{a}), T(\hat{a})) - \Psi(\mu, \nu) = -R_{\Omega(\hat{a})}\hat{z} = P_{\Omega(\hat{a})}\hat{z} - \hat{z}.$$
(30)

Recalling Lemma 3, (30) turns into

$$\langle P_{\Omega(\hat{a})}\hat{z} - \hat{z}, J(\hat{y} - P_{\Omega(\hat{a})}\hat{z}) \rangle \ge 0 \tag{31}$$

which yields,

 $\langle \rho(\varphi(\hat{a}) + \psi(S(\hat{a}), T(\hat{a}))) - \Psi(\mu, \nu), J(\hat{y}, P_{\Omega(\hat{a})}\hat{z}) \rangle \ge 0.$ 

Thus,  $\varphi(\hat{a}) = P_{\Omega(\hat{a})}[(1-\rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)]$ , and hence,  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$  admits a solution  $(\hat{a}, \mu, \nu)$ . Conversely, suppose  $(\hat{a}, \mu, \nu)$  solves  $EQVI(\mathcal{B}, \psi, \varphi, \Psi)$ , then

$$\varphi(\hat{a}) = P_{\Omega(\hat{a})}[(1-\rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)].$$
(32)

Utilizing the fact  $R_{\Omega(\hat{a})} = I_d - P_{\Omega(\hat{a})}$  and (32), we get

$$R_{\Omega(\hat{a})}[(1-\rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)] = (1-\rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu) - P_{\Omega(\hat{a})}[(1-\rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)].$$
(33)

Using (28)-(30), (33) turns into

$$\varphi(\hat{a}) + \rho^{-1} R_{\Omega(\hat{a})} \hat{z} = -\psi(S(\hat{a}), T(\hat{a})) + \rho^{-1} \Psi(\mu, \nu).$$

Thus,  $(\hat{z}, \hat{a}, \mu, \nu)$  is a solution of *EWHE*(27).

Now, we shall put forward the following iteration process by taking into consideration (28)-(29) and recalling the Nadlar's technique [36].

**Algorithm 2.** For initial points  $\hat{a}_0, \hat{z}_0 \in \mathcal{B}, \mu_0 \in A(\hat{a}_0), \nu_0 \in B(\hat{a}_0)$ , we estimate  $\{\hat{a}_n\}, \{\hat{z}_n\}, \{\mu_n\}, \{\nu_n\}$  as under:

$$\begin{aligned} \varphi(\hat{a}_{n}) &= P_{\Omega(\hat{a}_{n})}\hat{z}_{n}, \\ \hat{z}_{n+1} &= (1-\rho)\varphi(\hat{a}_{n}) - \rho\psi(S(\hat{a}_{n}), T(\hat{a}_{n})) + \Psi(\mu_{n}, \nu_{n}), \\ \mu_{n} &\in A(\hat{a}_{n}) : \|\mu_{n+1} - \mu_{n}\| \leq \mathcal{D}(A(\hat{a}_{n+1}), A(\hat{a}_{n}) + \pi^{n+1} \|\hat{a}_{n+1} - \hat{a}_{n}\| \\ \nu_{n} &\in B(\hat{a}_{n}) : \|\nu_{n+1} - \nu_{n}\| \leq \mathcal{D}(B(\hat{a}_{n+1}), B(\hat{a}_{n})) + \pi^{n+1} \|\hat{a}_{n+1} - \hat{a}_{n}\|. \end{aligned}$$
(34)

**Theorem 4.** Suppose that  $\varphi : \mathcal{B} \to \mathcal{B}$  be k-expanded,  $\delta$ -Lipschitz continuous mapping;  $\Psi, \psi : \mathcal{B} \times \mathcal{B} \to \mathcal{B}$  and  $S, T : \mathcal{B} \to \mathcal{B}$ be the single-valued mappings so that  $\psi(S,T)$  is  $\tau$ -strongly accretive regarding  $\varphi$  and  $\varsigma$ -Lipschitz continuous,  $\Psi$  is  $(\sigma, \upsilon)$ mixed Lipschitz continuous;  $A, B : \mathcal{B} \to CB(\mathcal{B})$  be  $\theta$ - $\mathcal{D}$ -Lipschitz continuous,  $\vartheta$ - $\mathcal{D}$ -Lipschitz continuous, respectively. If the retraction  $P_{\Omega(\hat{a})} : \mathcal{B} \to \Omega(\hat{a})$  comply with the Assumption C and constant  $\rho > 0$  satisfies:

$$\rho\delta + \sqrt{\delta^2 - 2\rho\tau + 64\varepsilon\varsigma^2} + (\sigma\theta + \upsilon\vartheta) < k - \xi, \tau < \frac{\delta^2 + 64\varepsilon\varsigma^2}{2\rho}.$$
(35)

Then the iterative sequences  $\{\hat{z}_n\}, \{\hat{a}_n\}, \{\nu_n\}$  produced by Algorithm 2 converges to  $\hat{z}, \hat{a}, \mu_n, \nu_n$ , respectively, and  $(\hat{z}, \hat{a}, \mu_n, \nu_n)$  so that  $\hat{z}, \hat{a} \in \mathcal{B}, \mu_n \in A(\hat{a}), \nu_n \in B(\hat{a})$  solves EWHE(27).

#### Proof. By implementing scheme (34), we get

$$\begin{aligned} \|\hat{z}_{n+2} - \hat{z}_{n+1}\| &= \|(1 - \rho)\varphi(\hat{a}_{n+1}) - \rho\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) + \Psi(\mu_{n+1}, \nu_{n+1}) \\ &- [(1 - \rho)\varphi(\hat{a}_n) - \rho\psi(S(\hat{a}_n), T(\hat{a}_n)) + \Psi(\mu_n, \nu_n)] \\ &\leq \rho \|\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_n)\| + \|\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_n) - \rho(\psi(S(\hat{a}_{n+1}), - T(\hat{a}_{n+1})))\psi(S(\hat{a}_n), T(\hat{a}_n)))\| + \|\Psi(\mu_{n+1}, \nu_{n+1}) - \Psi(\mu_n, \nu_n)\|. \end{aligned}$$
(36)

Since  $\varphi$  is  $\delta$ -Lipschitz continuous,  $\psi(S,T)$  is  $\tau$ -strongly accretive regarding  $\varphi$  and  $\varsigma$ -Lipschitz continuous, then

$$\begin{split} \|\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n}) - \rho(\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) - \psi(S(\hat{a}_{n}), T(\hat{a}_{n})))\|^{2} \\ \leq \|\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n})\|^{2} - 2\rho\langle\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) - \psi(S(\hat{a}_{n}), T(\hat{a}_{n}))), \\ J(\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n}) - \rho(\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) - \psi(S(\hat{a}_{n}), T(\hat{a}_{n})))) \\ \leq \|\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n})\|^{2} - 2\rho\langle\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) - \psi(S(\hat{a}_{n}), T(\hat{a}_{n}))), \\ J(\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n})\rangle + 2\rho\langle\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) - \psi(S(\hat{a}_{n}), T(\hat{a}_{n}))), \\ J(\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n}) - \rho(\psi(S(\hat{a}_{n+1}), T(\hat{a}_{n+1})) - \psi(S(\hat{a}_{n}), T(\hat{a}_{n}))) \\ - J(\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_{n})\rangle \\ \leq \delta^{2} \|\hat{a}_{n+1} - \hat{a}_{n}\|^{2} - 2\rho\tau \|\hat{a}_{n+1} - \hat{a}_{n}\|^{2} + 64\varepsilon\theta^{\|}\hat{a}_{n+1} - \hat{a}_{n}\|^{2} \\ = (\delta^{2} - 2\rho\tau + 64\varepsilon\varsigma^{2})\|\hat{a} - \hat{b}\|^{2}. \end{split}$$

Employing  $(\sigma, v)$ -mixed Lipschitz continuity of  $\Psi$ , and Lipschitz continuities of A and B yields

1

$$\begin{aligned} \|\Psi(\mu_{n+1}, \nu_{n+1}) - \Psi(\mu_{n}, \nu_{n})\| \\ &\leq \sigma \|\mu_{n+1} - \mu_{n}\| + \upsilon \|\nu_{n+1} - \nu_{n}\| \\ &\leq \sigma \mathcal{D}(A(\hat{a})_{n+1}), A(\hat{a}_{n})) + \upsilon \mathcal{D}(B(\hat{a}_{n+1}), B(\hat{a}_{n})) \\ &\leq \sigma (\theta + \pi^{n+1}) \|\hat{a}_{n+1} - \hat{a}_{n}\| + \upsilon (\theta + \pi^{n+1}) \|\hat{a}_{n+1} - \hat{a}_{n}\| \\ &= [\sigma (\theta + \pi^{n+1}) + \upsilon (\theta + \pi^{n+1})] \|\hat{a}_{n+1} - \hat{a}_{n}\|. \end{aligned}$$
(38)

Combining (37) and (38), we obtain

$$\|\hat{z}_{n+2} - \hat{z}_{n+1}\| \le [\rho\delta + \sqrt{\delta^2 - 2\rho\tau + 64\varepsilon\varsigma^2} + \sigma(\theta + \pi^{n+1}) + \upsilon(\vartheta + \pi^{n+1})] \|\hat{a}_{n+1} - \hat{a}_n\|.$$
(39)

Since  $\varphi$  is *k*-expanded, then

$$\begin{aligned} k \|\hat{a}_{n+1} - \hat{a}_n\| &\leq \|\varphi(\hat{a}_{n+1}) - \varphi(\hat{a}_n)\| \\ &= \|P_{\Omega(\hat{a}_{n+1})}\hat{z}_{n+1} - P_{\Omega(\hat{a}_n)}\hat{z}_n\| \\ &\leq [\|\hat{z}_{n+1} - \hat{z}_n\| + \xi \|\hat{a}_{n+1} - \hat{a}_n\|], \end{aligned}$$
(40)

that results in

$$|\hat{a}_{n+1} - \hat{a}_n|| \le \frac{1}{k - \xi} ||\hat{z}_{n+1} - \hat{z}_n||.$$
(41)

Making use of (41) into (39), we obtain

$$\|\hat{z}_{n+2} - \hat{z}_{n+1}\| \le \Gamma_n \|\hat{z}_{n+1} - \hat{z}_n\|,\tag{42}$$

where  $\Gamma_n = \frac{[\rho\delta + \sqrt{\delta^2 - 2\rho\tau + 64\varepsilon\varsigma^2} + \sigma(\theta + \pi^{n+1}) + \upsilon(\vartheta + \pi^{n+1})]}{k - \xi}$ . Indeed, the hypothesis  $\pi \in (0, 1)$ , results in  $\lim_{n \to \infty} \Gamma_n = \Gamma$ , where  $\Gamma = \frac{[\rho\delta + \sqrt{\delta^2 - 2\rho\tau + 64\varepsilon\varsigma^2} + (\sigma\theta + \upsilon\vartheta)]}{k - \xi}$ . By (35),  $\Gamma < 1$  and hence  $\{\hat{z}_n\}$  is a Cauchy sequence in  $\mathcal{B}$ . Then, we can find  $\hat{z} \in \mathcal{B}$  so that  $\lim_{n \to \infty} \hat{z}_n = \hat{z}$ . We can therefore conclude from (41), that  $\{\hat{a}_n\}$  is a Cauchy sequence in  $\mathcal{B}$  as well. One can find  $\hat{a} \in \mathcal{B}$  so that  $\lim_{n \to \infty} \hat{a}_n = \hat{a}$ . Invoking *A*'s Lipschitz continuity, we manifest that

$$\begin{aligned} \|\mu_{n+1} - \mu_n\| &\le \mathcal{D}(A(\hat{a}_{n+1}), A(\hat{a}_n)) + \pi^{n+1} \|\hat{a}_{n+1}) - \hat{a}_n\| \\ &\le (\theta + \pi^{n+1}) \|\hat{a}_{n+1} - \hat{a}_n\|. \end{aligned}$$
(43)

Since the sequence  $\{\hat{a}_n\}$  is Cauchy in  $\mathcal{B}$  and so is  $\{\mu_n\}$ . In the same manner, we manifest that  $\{\nu_n\}$  is Cauchy in  $\mathcal{B}$ . Hence  $\lim_{n \to \infty} \mu_n = \mu$  and  $\lim_{n \to \infty} \nu_n = \nu$  for some  $\mu, \nu \in \mathcal{B}$ . Since  $\mu_n \in A(\hat{a}_n)$ , then

$$d(\mu, A(\hat{a})) \| \leq \|\mu - \mu_n\| + d(\mu_n, A(\hat{a}))$$

$$\leq \|\mu - \mu_n\| + \mathcal{D}(A(\hat{a}_n), A(\hat{a}))$$

$$\leq \|\mu - \mu_n\| + \theta \|\hat{a}_n - \hat{a}\| + \pi^n \|\hat{a}_n - \hat{a}\|$$

$$= \|\mu - \mu_n\| + (\theta + \pi^n) \|\hat{a}_n - \hat{a}\| \to 0 \text{ as } n \to \infty.$$
(44)

Thus,  $d(\mu, A(\hat{a})) = 0$  and hence  $\mu \in A(\hat{a})$  and correspondingly,  $\nu \in B(\hat{a})$ . Consequently, we draw the conclusion that  $\hat{a}_n \to \hat{a}, \hat{z}_n \to \hat{z}, \mu_n \to \mu$  and  $\nu_n \to \nu$  and the continuity of the mappings  $P_{\Omega(\hat{a})}, \varphi, \psi, S, T, \Psi, A, B$ , we achieve  $\varphi(\hat{a}) = P_{\Omega(\hat{a})}\hat{z}$ , where,  $\hat{z} = (1 - \rho)\varphi(\hat{a}) - \rho\psi(S(\hat{a}), T(\hat{a})) + \Psi(\mu, \nu)$ , which amounts to say  $(\hat{z}, \hat{a}, \mu, \nu)$  is a solution of EWHE(27).

## **CONFLICTS OF INTEREST**

The authors declare no conflict of interest.

#### REFERENCES

- A. Adamu, D. Kitkuan, A. Padcharoen, C. Chidume, and P. Kumam, "Inertial viscosity-type iterative method for solving inclusion problems with applications," *Math. Comput. Simulation*, vol. 194, pp. 445–459, 2022.
- [2] R. P. Agarwal, D. O. Regan, and D. R. Sahu, "Iterative construction of fixed points of nearly asymptotically nonexpansive mappings," J. Nonlinear Convex Anal., vol. 8, no. 18, pp. 61–79, 2007.
- [3] M. Akram, "On generalized Yosida inclusion problem with application," *Results in Control and Optimization*, vol. 11, 2023. https://doi.org/10.1016/j.rico.2023.100223.
- [4] M. Akram and M. Dilshad, "A unified inertial iterative approach for general quasi variational inequality with application," *Fractal Fract.*, vol. 6, 2022. https://doi.org/10.3390/fractalfract6070395.
- [5] M. Akram, A. Khan, and M. Dilshad, "Convergence of some iterative algorithms for system of generalized set-valued variational inequalities," J. Funct. Spaces, 2021. https://doi.org/10.1155/2021/6674349.
- [6] T. O. Alakoya and O. T. Mewomo, "S-Iteration inertial subgradient extragradient method for variational inequality and fixed point problems," Optimization, 2023. https://doi.org/10.1080/02331934.2023.2168482.
- [7] F. Alvarez, "Weak convergence of a relaxed and inertial hybrid projection-proximal point algorithm for maximal monotone operators in Hilbert space," SIAM J. Optim., vol. 14, pp. 773–782, 2004.
- [8] C. Baiocchi and A. Capelo, "Variational and Quasi Variational Inequalities: Applications to free boundary problems," Wiley, New York, 1984.
- [9] A. Bensoussan and J.-L. Lions, "Impulse Control and Quasi-variational Inequalities," Gauthier-Villars, Paris, 1984.
- [10] P. Beremlijski, J. Haslinger, M. Ko<sup>\*</sup>cvara, and J. Outrata, "Shape optimization in contact problems with Coulomb friction," SIAM J. Optim., vol. 13, no. 2, pp. 561–587, 2002.
- [11] M. C. Bliemer and P. H. Bovy, "Quasi-variational inequality formulation of the multiclass dynamic traffic assignment problem," *Transportation Res. Part B*, vol. 37, no. 6, pp. 501–519, 2003.
- [12] S. S. Chang, A. Ahmadini, Salahuddin, M. Liu, and J. Tang, "The optimal control problems for generalized elliptic quasi variational inequalities," *Symmetry*, 2022. https://doi.org/10.3390/sym14020199.
- [13] A. K. Çopur, E. Hacioğlu, F. Gursoy, and M. Erturk, "An efficient inertial type iterative algorithm to approximate the solutions of quasi variational inequalities in real Hilbert spaces," J. Sci Comput., vol. 89, 2021. https://doi.org/10.1007/s10915-021-01657-y.
- [14] K. Iqbal, S. M. Muslim Raza, M. M. Butt, H. Ahmad, and S. Askar, "On exploring the generalized mixture estimators under simple random sampling and application in health and finance sector," *AIP Advances*, vol. 14, no. 1, 2024.
- [15] S. Dey and S. Reich, "A novel inertial Tseng's method for solving generalized variational inequality problem," Optimization, 2023. https://doi.org/10.1080/02331934.2023.2173525.
- [16] M. Dilshad, A. Aljohani, and M. Akram, "Iterative scheme for split variational inclusion and a fixed-Point problem of a finite collection of nonexpansive mappings," J. Funct. Spaces, 2020. https://doi.org/10.1155/2020/3567648.
- [17] J. Eckstein and D. Bertsekas, "On the Douglas-Rachford splitting method and the proximal point algorithm for maximal monotone operators," *Math. Program.*, vol. 8, no. 18, pp. 61–79, 1992.
- [18] D. Filali, M. Dilshad, L. S. M. Alyasi, and M. Akram, "Inertial iterative algorithms for split variational inclusion and fixed point problems," *Axioms*, vol. 12, 2023. https://doi.org/10.3390/axioms12090848.
- [19] Y. Guo and W. Wang, "Strong convergence of a relaxed inertial three-operator splitting algorithm for the minimization problem of the sum of three or more functions," J. Nonlinear Funct. Anal., vol. 41, pp. 1–19, 2021.
- [20] B. Halpern, "Fixed points of nonexpanding maps," Bull. Amer. Math. Soc., vol. 73, p. 957–961, 1967.
- [21] P. T. Harker, "Generalized Nash games and quasi-variational inequalities," Eur. J. Oper. Res., vol. 54, no. 1, pp. 81–94, 1991.
- [22] M. Hintermuller and C. N. Rautenberg, "Parabolic quasi-variational inequalities with gradient-type constraints," SIAM J. Optim., vol. 23, no. 4, pp. 2090–2123, 2013.
- [23] M. Hintermuller and C. N. Rautenberg, "A sequential minimization technique for elliptic quasi-variational inequalities with gradient constraints," SIAM J. Optim., vol. 22, no. 4, pp. 1224–1257, 2012.
- [24] S. Ishikawa, "Fixed points by a new iteration method," Proc. Amer. Math. Soc., vol. 44, pp. 147–150, 1974.
- [25] J. Kalker, "Contact mechanical algorithms," Comm. Appl. Numer. Meth., vol. 4, pp. 25–32, 1988.
- [26] Z. Kan, F. Li, H. Peng, B. Chen, and X. G. Song, "Sliding cable modeling: A nonlinear complementarity function based framework," *Mech. Syst. Signal Pr.*, vol. 146, pp. 1–20, 2021.
- [27] A. S. Kravchuk and P. J. Neittaanmaki, "Variational and Quasi-Variational Inequalities in Mechanics," Springer, Dordrecht, vol. 147, 2007.

- [28] M. Kunze and J. F. Rodrigues, "An elliptic quasi-variational inequality with gradient constraints and some of its applications," *Math. Methods Appl. Sci.*, vol. 23, no. 10, pp. 897–908, 2000.
- [29] H. Ahmad and T. A. Khan, "Variational iteration algorithm i with an auxiliary parameter for the solution of differential equations of motion for simple and damped mass-spring systems," *Noise & Vibration Worldwide*, vol. 51, no. 1-2, pp. 12–20, 2020.
- [30] Q. Liu, "A convergence theorem of the sequence of Ishikawa iterates for quasi-contractive mappings," J. Math. Anal. Appl., vol. 146, no. 2, pp. 301–305, 1990.
- [31] X. P. Luo, Y. B. Xiao, and W. Li, "Strict feasibility of variational inclusion problems in reflexive Banach spaces," J. Ind. Manag. Optim., vol. 16, no. 5, pp. 2495–2502, 2020.
- [32] P. E. Maingé, "Convergence theorems for inertial KM-type algorithms," J. Comput. Appl. Math., vol. 219, no. 1, 2008.
- [33] P. E. Maingé, "Regularized and inertial algorithms for common fixed points of nonlinear operators," *J. Math. Anal. Appl.*, vol. 344, pp. 876–887, 2008.
- [34] M. A. Malik, M. I. Bhat, and B. Zahoor, "Solvability of a class of set-valued implicit quasi-variational inequalities: A Wiener–Hopf equation method," *Results in Control and Optimization*, vol. 9, 2022. https://doi.org/10.1016/j.rico.2022.100169.
- [35] W. R. Mann, "Mean value methods in iteration," Proc. Amer. Math. Soc., vol. 4, pp. 506–510, 1953.
- [36] S. B. Nadlar, "Multi-valued contraction mapping," Pacific J. Math., vol. 30, no. 3, pp. 475–488, 1969.
- [37] M. A. Noor and W. Oettli, "On general nonlinear complementarity problems and quasi equilibria," Le Mathematiche, vol. 49, pp. 313–331, 1994.
- [38] M. A. Noor, K. I. Noor, and B. B. Mohsen, "Some new classes of general quasi variational inequalities," *AIMS Mathematics*, vol. 6, no. 6, pp. 6406–6421, 2021.
- [39] H. Ahmad, T. A. Khan, and S.-W. Yao, "An efficient approach for the numerical solution of fifth-order kdv equations," *Open Mathematics*, vol. 18, no. 1, pp. 738–748, 2020.
- [40] M. A. Noor and K. Noor, "Iterative schemes for solving general variational inequalities," *Differential Equations & Applications*, vol. 15, no. 2, pp. 113–134, 2023.
- [41] M. A. Noor, "Some developments in general variational inequalities," Appl. Math. Comput., vol. 152, pp. 199-277, 2004.
- [42] J. Outrata, M. Kočcvara, and J. Zowe, "Nonsmooth Approach to Optimization Problems with Equilibrium Constraints, Theory, Applications and Numerical Results," *Kluwer Academic Publishers, Dordrecht*, 1998.
- [43] B. T. Polyak, "Some methods of speeding up the convergence of iteration methods," USSR Comput. Math. Math. Phys., vol. 4, no. 5, pp. 1–17, 1964.
- [44] L. F. Richardson, "The approximate arithmetical solution by finite differences of physical problems involving differiential equations with an application to the stresses in a masonry dam," *Philos. Trans. R. Soc. Lond.*, vol. 201, pp. 307–357, 1911.
- [45] D. R. Sahu, "Applications of accelerated computational methods for quasi-nonexpansive operators to optimization problems," Soft Comput., vol. 24, pp. 17887–17911, 2020.
- [46] D. R. Sahu, "A unified framework for three accelerated extragradient methods and further acceleration for variational inequality problems," Soft Comput., vol. 27, pp. 15649–15674, 2023.
- [47] L. Scrimali, "Quasi-variational inequalities in transportation networks," Math. Models Methods Appl. Sci., vol. 14, no. 10, pp. 1541–1560, 2004.
- [48] Y. Shehu and A. Gibali, "Inertial Krasnoselskii-Mann method in Banach spaces," *Mathematics*, vol. 8, 2020. https://doi.org/10.3390/math8040638.
  [49] N. Song, H. Peng, X. Xu, and G. Wang, "Modeling and simulation of a planar rigid multibody system with multiple revolute clearance joints based
- on variational inequality," *Mech. Mach. Theory*, vol. 154, 2020. https:// doi.10.1016/j.mechmachtheory.2020.104053.
  [50] G. Stampacchia, "Formes bilineaires coercivites sur les ensembles convexes," *Comptes Rendus de l'Academie des Sciences*, vol. 258, pp. 4413–4416, 1964.
- [51] Y. Wang, T. Xu, J. Yao, and B. Jiang, "Sef-adaptive method and inertial modification for solving the split feasibility problem and fixed point problem of quasi-nonexpansive mapping," *Mathematics*, vol. 10, 2022. https://doi.org/10.3390/math10091612.